

Q1 (a) $f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} (a_n \cos(\frac{n\pi x}{L}) + b_n \sin(\frac{n\pi x}{L}))$

$$a_n = \frac{1}{L} \int_{-L}^L f(x) \cos(\frac{n\pi x}{L}) dx, \quad b_n = \frac{1}{L} \int_{-L}^L f(x) \sin(\frac{n\pi x}{L}) dx$$

(b) $f(x) = |x| \Rightarrow b_n = 0$, as odd part is zero.

$$a_n = \frac{2}{\pi} \int_0^{\pi} x \cos nx dx, \quad a_0 = \frac{2}{\pi} \left[\frac{x^2}{2} \right]_0^{\pi} = \pi$$

$$\text{For } n > 0, \frac{\pi a_n}{2} = \left[\frac{-x \sin nx}{n} \right]_0^{\pi} + \int_0^{\pi} \frac{\sin nx}{n} dx$$

$$= \left[\frac{\cos nx}{n^2} \right]_0^{\pi} = \frac{(-1)^n - 1}{n^2}. \quad a_n = \begin{cases} \frac{4}{\pi n^2}, & n \text{ odd} \\ 0, & \text{otherwise} \end{cases}$$

$$\text{Thus } f(x) = \frac{\pi}{2} - \frac{4}{\pi} \sum_{m=1}^{\infty} \frac{\cos((2m-1)x)}{(2m-1)^2}$$

(c) $\frac{1}{L} \int_{-L}^L f^2(x) dx = \frac{a_0^2}{2} + \sum_{n=1}^{\infty} (a_n^2 + b_n^2)$

$$(d) \frac{1}{\pi} \int_{-\pi}^{\pi} |x|^2 dx = \frac{2\pi^2}{3} = \frac{1}{2} \frac{\pi^2}{4} + \frac{16}{\pi^2} \sum_{m=1}^{\infty} \left(\frac{1}{(2m-1)^2} \right)^2$$

$$\Rightarrow \frac{\pi^4}{96} = \sum_{m=1}^{\infty} \frac{1}{(2m-1)^4} \Rightarrow \pi^4 = 96 \sum_{m=1}^{\infty} \frac{1}{(2m-1)^4}$$

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Q2 (a)

$$\epsilon_{ijk} \epsilon_{klm} = \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}$$

$$(b) (\text{curl}(\underline{A} \times \underline{B}))_i = \epsilon_{ijk} \partial_j (\underline{A} \times \underline{B})_k = \epsilon_{ijk} \epsilon_{klm} \partial_j (A_l B_m)$$

$$= (\delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}) ((\partial_j A_l) B_m + A_l (\partial_j B_m))$$

$$= (\partial_j A_j) B_i + A_i (\partial_j B_j) - (\partial_j A_i) B_j - A_j (\partial_j B_i)$$

$$= [\underline{B} \cdot \nabla \underline{A} + \underline{A} (\text{div} \underline{B}) - (\text{div} \underline{A}) \underline{B} - \underline{A} \cdot \nabla \underline{B}]_i \quad \text{qed.}$$

$$(c) \underline{A} \times \underline{B} = \underline{i} \times (x\underline{i} + y\underline{j} + z\underline{k}) = y\underline{k} - z\underline{j}$$

$$\text{curl}(\underline{A} \times \underline{B}) = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ \partial_x & \partial_y & \partial_z \\ 0 & -z & y \end{vmatrix} = (1+1)\underline{i} + 0\underline{j} + 0\underline{k} = 2\underline{i}$$

$$\underline{B} \cdot \nabla \underline{A} - \underline{B} \cdot \nabla \underline{A} - \underline{A} \cdot \nabla \underline{B} + \underline{A} \cdot \nabla \underline{B}$$

$$= 0 + 0 - \frac{\partial}{\partial x} (x, y, z) + \underline{i} \cdot 3$$

$$= -\underline{i} + 3\underline{i} = 2\underline{i} \quad \text{qed.}$$

Q 3 (a) Take $x = 3 \cos \theta$, $y = 2 \sin \theta$, $z = 0$

$$\theta \in [0, 2\pi). \quad \underline{dr} = (-3 \sin \theta, 2 \cos \theta, 0) d\theta$$

$$\begin{aligned} \oint_C &= \int_0^{2\pi} ((2 \times 3 \cos \theta - 2 \sin \theta)(-3 \sin \theta) + (2 \times 2 \sin \theta - 3 \cos \theta) 2 \cos \theta) d\theta \\ &= \int_0^{2\pi} (6 \sin^2 \theta + 6 \cos^2 \theta) d\theta \quad \text{as the other terms } \int = 0. \\ &= \int_0^{2\pi} 6 d\theta = 12\pi \end{aligned}$$

(b) (i) $\int_C (y, z, yx) \cdot \underline{dr} = \int_C (t^3, t, t^5) \cdot (2t, 3t^2, 1) dt$

$$= \int_C (2t^4 + 3t^3 + t^5) dt = \frac{2}{5} + \frac{3}{4} + \frac{1}{6}$$

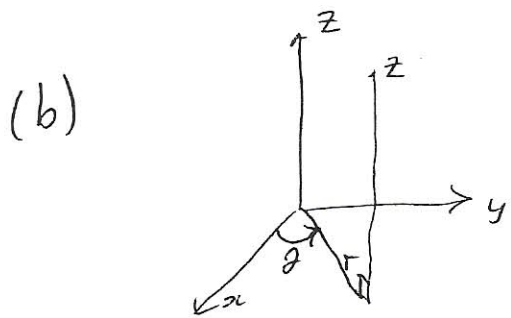
$$= \frac{79}{60}$$

(ii) $\int_C = \int_C (t^2, t, t^3) \cdot (1, 2t, 1) dt$

$$= \int_C (t^2 + 2t^2 + t^3) dt = \frac{3}{3} + \frac{1}{4} = \frac{5}{4}$$

The end points in case (i) and (ii) are the same but the values of \int_C are different, hence \underline{G} is not conservative.

Q 4(a) $\frac{\partial(x, y, z)}{\partial(u, v, w)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & \frac{\partial z}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & \frac{\partial z}{\partial v} \\ \frac{\partial x}{\partial w} & \frac{\partial y}{\partial w} & \frac{\partial z}{\partial w} \end{vmatrix}$



$(x, y, z) = (r \cos \theta, r \sin \theta, z)$
 $r > 0, \theta \in [0, 2\pi), z \in (-\infty, \infty)$

(c) $\frac{\partial(x, y, z)}{\partial(r, \theta, z)} = \begin{vmatrix} \cos \theta & \sin \theta & 0 \\ -r \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta$

$= r$

(d) $\int_V (1+z^3) \exp(x^2+y^2) dV = \int_V \exp(x^2+y^2) dV$ by symmetry

$= \int_0^1 \int_0^{2\pi} \int_{-1}^1 r e^{r^2} dz d\theta dr = 4\pi \int_0^1 r e^{r^2} dr$

$= 2\pi \int_0^1 e^u du = 2\pi (e-1)$

Q5 (a)



$$\int_V \operatorname{div} \underline{A} \, dV = \int_S \underline{A} \cdot \underline{n} \, dS$$

where \underline{n} = (unit outward normal to S).

$$(b) \quad \underline{E} = -\nabla \phi = -\nabla \frac{1}{r} = \frac{\underline{r}}{r^3}$$

$$\operatorname{div} \underline{E} = \nabla \cdot \left(\frac{\underline{r}}{r^3} \right) = \frac{\nabla \cdot \underline{r}}{r^3} - 3 \frac{\underline{r} \cdot \underline{r}}{r^5} = \frac{3}{r^3} - \frac{3}{r^3} = 0,$$

if $r \neq 0$.

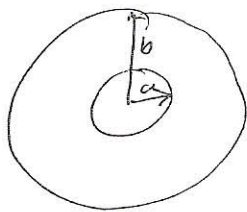
$$(c) \quad I = \int_{V_a} \operatorname{div} \underline{E} \, dV = \int_{S_a} \underline{E} \cdot \underline{n} \, dS, \text{ where } \underline{n} = \frac{\underline{r}}{r}$$

$$\text{So } I = \int_{S_a} \left(\frac{\underline{r}}{r^3} \cdot \frac{\underline{r}}{r} \right) dS = \int_{S_a} \left(\frac{1}{r^2} \right) dS$$

$$= \int_{S_a} \frac{1}{a^2} dS = \frac{1}{a^2} \int_{S_a} 1 \, dS = \frac{1}{a^2} |S| = \frac{1}{a^2} 4\pi a^2 = 4\pi.$$

$$\underline{I = 4\pi}$$

Consider the ball of radius a inside the ball of radius $b > a$

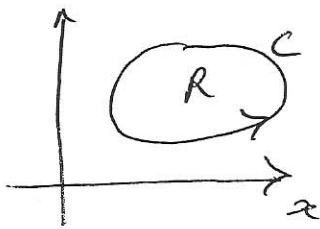


$$\int_{V_a} + \int_{V_b - V_a} = \int_{V_b}$$

But the region $a \leq r \leq b$ has $\operatorname{div} \underline{E} = 0$,

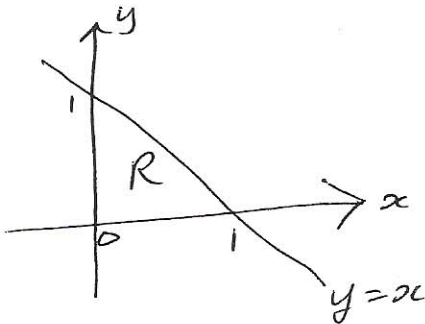
$$\text{so } \int_{V_b - V_a} = 0, \text{ giving } \int_{V_a} = \int_{V_b} \text{ qed.}$$

Q 6 (a)



$$\oint_C (P dx + Q dy) = \int_R \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right)$$

(b)

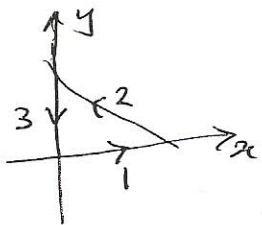


$$\int_R = \int_R (2(1+x+y) - x) dx dy$$

$$= \int_R (2 + x + 2y) dx dy = 2|R| + \int_R x + 2y dx dy$$

$$= 2 \times \frac{1}{2} + 3 \int_R x dx dy \quad (\text{by symmetry}) = 1 + 3 \int_0^1 \int_0^{1-y} x dx dy$$

$$= 1 + 3 \int_0^1 \frac{1}{2} (1-y)^2 dy = 1 + 3 \times \frac{1}{2} \times \frac{1}{3} = 1 + \frac{1}{2} = \frac{3}{2}$$



On C_1 , $y=0$, so $\int_{C_1} (P dx + Q dy) = \int_{C_1} (0 dx + Q dy) = 0$

On C_2 , $dx = -dy$ so $\int_{C_2} (P dx + Q dy) = \int_{C_2} (Q - P) dy$

$$= \int_0^1 [(1+1)^2 - y(1-y)] dy = 4 - \int_0^1 (y - y^2) dy = 4 - \frac{1}{2} + \frac{1}{3}$$

On C_3 , $x=0$, so $\int_{C_3} (P dx + Q dy) = \int_1^0 (P \times 0 + (1+y)^2) dy$

$$= \int_1^0 (1+y)^2 dy = - \left[\frac{(1+y)^3}{3} \right]_0^1 = - \left(\frac{2}{3} - \frac{1}{3} \right) = - \frac{1}{3}$$

Thus $\int_C = 0 + 4 - \frac{1}{2} + \frac{1}{3} - \frac{1}{3} = 4 - \frac{1}{2} - 2 = \frac{3}{2}$

$= \int_R$ ged.